

Report of Working Group I
Convenors: Koscielniak & Machida
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I Thanks to our hosts

II Much of the "to do" list from April '04 workshop has been accomplished (between or during this w/s)

- public relations & community recognition effort continues with AIP proceedings for this workshop
- tracking studies of resonance crossing
⇒ tolerances on alignment + gradient errors
- improved cost model for μ FFAG including externalities such as the experiment (detector)
- finding a home (may be?) for e-model
- diagnostic strategy for e-model.

III Exciting development
isochronous semi-scaling FFAG

$\gamma = \gamma_t$ Rees
 $\gamma > \gamma_t$ Schönauer



Isochronous semi-scaling FFAG # free params > # turns

Rees Cell has 5 magnets. Ability to adjust $B_0 + B_1$ (field, gradient) for each orbit leads to nonlinear magnets $\gamma = \gamma_t$
Compared to Carol's 1.2km 3-element lattice, new approach $\Delta T/T_0 \sim 10^{-5}$ allows longer straights, fewer cells.

Schönauer has simplified lattice somewhat, $\gamma > \gamma_t$. particularly geometry of elements

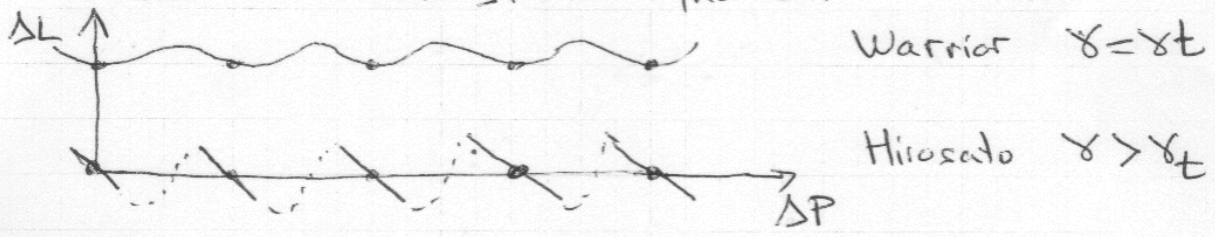
Rees m/c \Rightarrow on-crest acceln, resistive loading of cavity.

Schönauer \Rightarrow off-crest acceln with synchrotron style bucket

Rees m/c holds promise of near perfect isochronism + zero chromaticity.

Should be pursued.

Need to identify functional form of residual ΔT - understand limits to longitudinal dynamics.



BUT nonlinearity may be inconsistent with huge \perp acceptance

Need tracking studies to identify influence of nonlinear resonances (Meot, etc)



Non-scaling μ FFA& (S. Berg)

Have an improved cost model for accelerator components.
 - e.g. includes fixed-costs of magnet fabrication.

Market economy approach to decision making to Milton Friedman.
 However, like trans-national corporations,
 we have been externalising costs, and passing them on to
 the experiment.

Cost model now includes marginal increase of detected cost
 with respect to μ decay loss.

Cost function no longer flat, and small rings with
 strong bend fields are now favoured. (just as they were a
 year ago!)

Cost model has still room for improvement.

- include measurement of operating costs
- internalize cost to μ -cooling of FFA& aperture selection.
- find a cost-function to inform our choice of

$$(a, b) = \left[\frac{\delta E}{\delta E \omega \delta T}, \frac{\delta T_2}{\delta T_1} \right]$$

i.e. quantify the cost of non-linear emittance distortion.

Some aspects of this issue quantified by Koscielnyak
 (dwell time, acceleration efficiency, time dispersion).

 \bar{z}
 $\langle \cos x \rangle$

$$\frac{1}{2!} \frac{\delta^2 \bar{z}}{\delta H^2}$$



Electron Model -

- i) Most significant development is enthusiasm of Daresbury and RAL to consider hosting ~~the~~ e-model. Possibility to realise hard work and creativity of last 4 years is exciting and rewarding.

Under ASTEC initiative an 8-35 MeV ~~est~~ electron energy recovery linac, with variety of time structure, is constructed in next two years.

- ii) Issue is choice of RF

e-model : S-band (3 GHz)

recuperte SRS equipment?

linac : L-band (1.3 GHz)

single bunch operation decouples RF choice between machines and will ease kicker rise/fall requirements also.

Cost/opinions of Kazushi Hanakawa

3.3 GHz	single klystron, waveguide distribution	good option
1.3 GHz	ditto	not ruled out
0.85 GHz	30 IOT + low-level RF	rejected

[Three ugly sisters, no Cinderella here]

~~New~~ requirements to feed into e-model

range of $a = [0, \frac{1}{4}]$ subspace $[0, \infty]$
of

New \Rightarrow of $b = [0, \frac{1}{2}]$ $[0, 1]$

\Rightarrow tunability of RF or ring circumference



Electron Model Continued.

iii) Tracking Studies of Resonance Crossing.

[Also nice experimental studies @ PoP & HIMAC by Aiba]

The studies give confidence that integer + 1/2 integer resonances may be crossed with negligible \downarrow emittance blow up. Keil reported study at April workshop (his own lattice?) Machida presented studies using SIMPSONS here with Trbojevic + Cowart lattice.

Tolerances are demanding but achievable:

alignment	< 30 μ m rms, gaussian (Keil)	} 5 turns limit
	< 50 μ m 100%, uniform (Machida)	
gradient error	< 0.5%	0.1% achieved JPARC

Machida also reported synchro-betatron type effect due to m/c errors changes of pathlength \Rightarrow reduced asynchronism

iv) Practicalities of alignment, etc.

- a) single concrete slab for entire machine
- b) two cells per girder - alignment within girder 10 μ m (use laser tracker and piezo actuators)
- c) alignment between girders using central laser tracker < 50 μ m
- d) support vacuum chamber independently of magnets
- e) laser tracker needs clear line of sight unobstructed by λ guides

To achieve ~~the~~ better accuracy use beam-based alignment

Electron Model continued

v) Diagnostics

- closed orbit BPMs : 2 per plane per cell.
with 3cm aperture, 3 μ m resolution possible
BUT needs extreme care over low noise electronics.

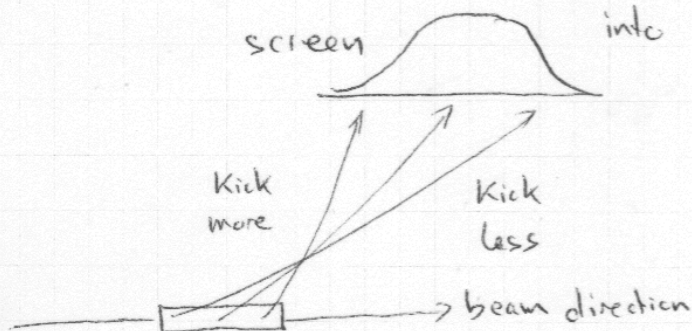
BPMs used also to infer beam momentum. [No spectrometer]
(distinguish \perp & \parallel ?)

- \perp emittance measurement

No option but to kick out \perp to emittance rig
- pepper-pot plate, fluorescent screen + CCD camera.
[Whole bunch gets same kick]

- longitudinal profile

time structure is beyond reach of wall-current monitor.
Use transverse-deflecting cavity and fluorescent screen
Kick varies along bunch \Rightarrow time dependence converted
into position dependence



BUT centreline
from which
we kick changes
with momentum

- exploration of longitudinal phase-space vastly facilitated by continuous energy variability of linac.
- may also help study resonance crossing.



Electron Model Continued.

vi) SPECULATION

One ~~practical~~ key purpose of the model is to benchmark the scaling laws for resonance crossing.

e-model should demonstrate x-ing speeds at least as slow as μ FFAG — without need to install LF cavity.

Suggestion (Koscielniak) that crude measure of speed is

$$s \equiv \frac{1}{N_c N_t} = \frac{\Delta P \langle \cos x \rangle}{\Delta P} = \alpha (\omega \Delta T)$$

Criterion for ~~an~~ e-model $s_e \leq s_\mu$?

Keil's EPACO4 lattice is a move in correct direction $N_c \uparrow, L_0 \downarrow$
Is it good enough?

vii) "To do"

- injection & extraction — details & concepts!
- costings

A crossing speed argument

relevant parameter is $\frac{\dot{v}}{v} = \frac{\dot{\phi}}{\phi}$ $v = \text{tune}$
 $\phi = \text{cell phase advance}$

machine with large # cells has larger Δv , but time to cross is longer also because also proportional to N_{cell} .

To lowest order, relation between ϕ and quad strength

$$A \equiv \frac{B L c}{P} \quad B = \text{field}, p = \text{momentum}, L = \text{length}$$

$$A^2 \approx \frac{3(1 - \cos \phi)}{L_0 (L_d + L_f + 3L_0)} \quad L_0 = \text{cell length}, L_0 = \text{drift length}$$

$$\therefore \frac{(1 - \cos \phi) @ \text{injection}}{(1 - \cos \phi) @ \text{extraction}} = \left(\frac{\frac{1}{P}}{\frac{1}{P}} \right)^2$$

Hence if ratio of injection to extraction momenta are equal between two machines, then

crossing speed proportional $\frac{1}{N_c N_t} \leftarrow \# \text{ turns}$

$$\text{BUT } N_c N_t \underset{\substack{\uparrow \\ \text{per cell impulse}}}{SP} \langle \cos \pi c \rangle = \underset{\substack{\uparrow \\ \text{machine range}}}{\Delta P} \Delta P$$

Hence crossing speed $\propto \frac{SP \langle \cos \pi c \rangle}{\Delta P}$ reducing range alone does not reduce ring speed

$$\text{Now } \frac{SP}{\Delta P} = \underset{\substack{\downarrow \\ \text{Scott's param}}}{W} (\omega \Delta T) \gg \frac{1}{24} \omega \Delta T$$

So lower frequency ω , or ToF range ΔT to reduce crossing speed.

For optimised FFAG lattice

$$\Delta T = \frac{3}{4} \frac{(\hat{p} - \check{p})^2}{(\check{p})^2} \frac{\Theta^2}{(1 - \cos\phi)} T_0 \quad (1)$$

$\Theta =$ bend angle of half cell $= \pi/N_c$

$T_0 =$ T₀F across cell at reference energy

Now for gutter acceleration $\frac{\delta P}{\Delta P} = \omega(\omega \Delta T) > \frac{1}{24} \omega \Delta T$

All other params being equal, we are interested to scale ωT_0 between μ and e machines.

$$\omega T_0 = \frac{\omega}{c} [L_{\text{magnet}} + L_{\text{RF}}] \quad L = \text{"length"}$$

$$L_{\text{RF}} \approx \frac{3}{4} \lambda = \frac{3}{2} \frac{c}{\omega} \pi$$

$$L_{\text{magnet}} \approx \frac{3 \bar{p} \pi}{e B N_c} \quad \begin{matrix} B = \text{field, } e = \text{charge} \\ \bar{p} = (\hat{p} + \check{p})/2 \end{matrix}$$

$$\omega T_0 \approx \frac{\omega}{c} \frac{3 \bar{p} \pi}{e B N_c} + \frac{3\pi}{2}$$

Now for the scalings...

[Ideally ratio $L_{\text{mag}}/L_{\text{RF}}$ should be same between machines] ↙ not too important

$$\frac{\bar{p}(\mu)}{\bar{p}(e)} = 10^3 \quad \text{which gives mm magnet lengths}$$

∴ back off the field, B 4 Tesla → 0.2 Tesla

⇒ magnet length ≈ 10cm for combined function "D"

$\frac{L_{mag}(\mu)}{L_{mag}(e)} = \frac{10^3}{20} = 50$ and wavelength λ to be scaled in same way.

$\frac{RF(e)}{RF(\mu)} = 50 \therefore RF(e) = 10 \text{ GHz}$
 $RF(\mu) = 0.2 \text{ GHz}$

BUT the structure is awfully small (fiddly)
 Scott reduced frequency by factor 3. $RF \Rightarrow 3 \text{ GHz}$.


$\omega T_0 \approx \frac{3\pi}{2} + \frac{\omega}{c} \frac{3 \langle p \rangle \Theta}{e B}$ $\omega \Rightarrow \frac{50\omega}{3}$ $\frac{\langle p \rangle}{B} \Rightarrow \frac{1}{50} \frac{\langle p \rangle}{B}$
 $\Rightarrow \frac{3\pi}{2} + \frac{\omega}{c} \frac{1 \langle p \rangle \Theta}{e B}$ $\Theta \Rightarrow 3\Theta, N_{cell} \Rightarrow \frac{N_{cell}}{3}$

BUT look at formula ① and Θ^2 term
 This electron model is a harder machine than 10-20 GeV μ
 despite fact that frequency is artificially low.

In its present form, x-ing speed is faster!
 To make it lower, either $\omega \downarrow$ or $N_c \uparrow$ (1.3 GHz?)
 → smaller frequency sweep

Note The demonstration model will test
 i) gutter acceleration ii) resonance crossing

BUT it cannot do these simultaneously } → phase II
 except at high crossing speed. LF

If acceleration is in buckets  or $\Delta T_2 = 0$
 still cannot get slow x-ing speed.

e.g. $b=0$ range $\propto a^{1/3}$ $\tau \propto 1/a^{2/3}$

x-ing speed $\propto \frac{\text{range}}{\text{dwell}} = a = \frac{\delta P}{\Delta P \omega \Delta T}$

A step backward, but its important to understand scenarios

- "as is" e-model $\left\{ \begin{array}{l} \text{x-ing speed faster than } \mu \\ \text{future LF system to lower speed} \end{array} \right.$
- revise e-model $N_{\text{cell}} \uparrow$ and/or $\omega \downarrow$
 \Rightarrow x-ing speed same as 10-20 GeV μ
 - still need LF system to get to low x-ing speeds
- Both cases flat-topping could, maybe, halve x-ing speed.

What is scaling law?

$$\frac{1}{\alpha} \frac{SP}{\Delta P} = \omega \Delta T = \frac{3 \Delta P^2 \theta^2}{4 (\frac{v}{c})^2 (1 - \cos \phi)} \left[\frac{\omega 3 \langle p \rangle \theta}{c e B} + \frac{3\pi}{2} \right]$$

Want $\omega \Delta T$ small \therefore prefer NOT $\propto \theta^3 \Rightarrow \omega \downarrow$
 Could be argument for 1.3 GHz?