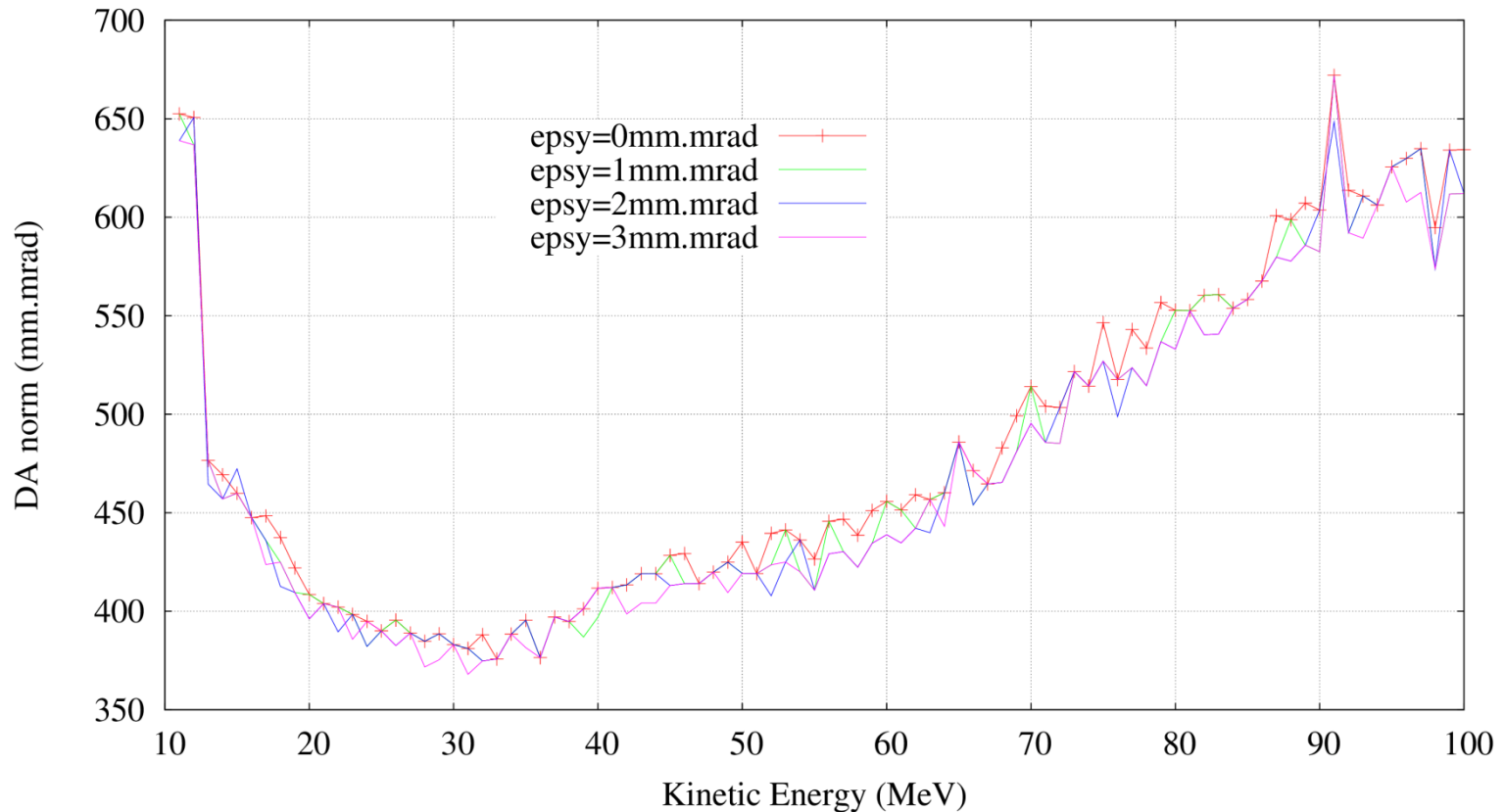


KURRI scaling FFAG studies:

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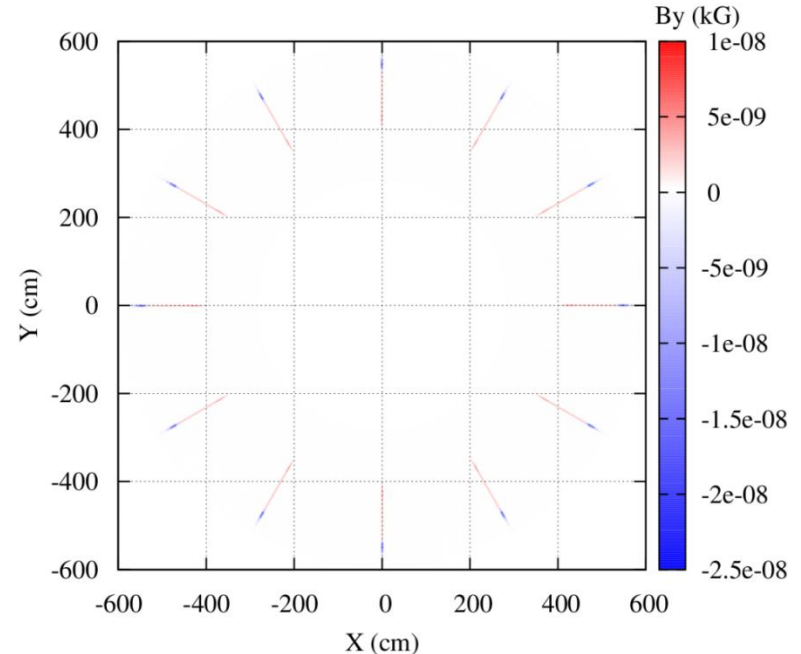
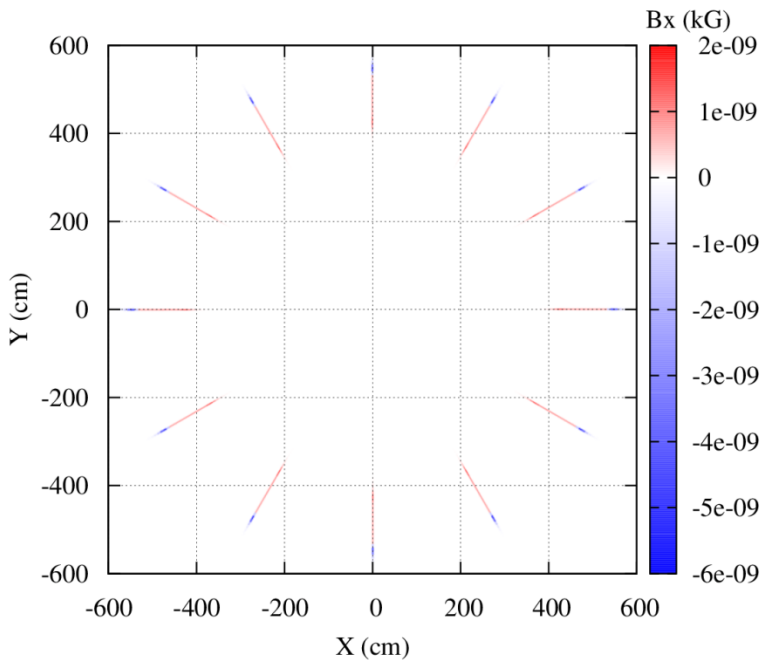
DA of the KURRI FFAG with 3D tosca map



The Dynamic Acceptance is around 375 mm.mrad and seems insensitive to the vertical amplitude
Vertical amplitude limited to +/-1cm, i.e. 3 mm.mrad

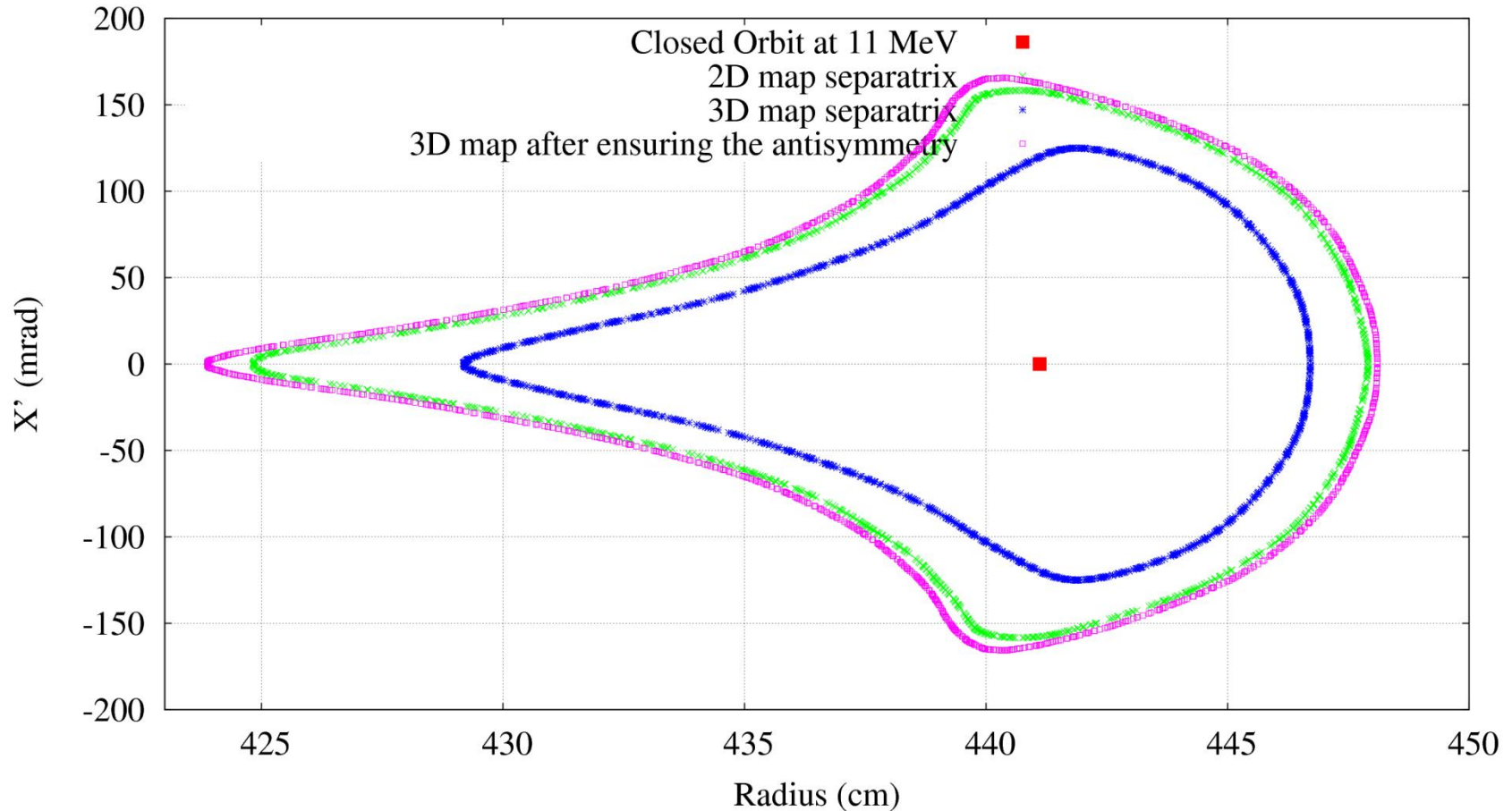
Median plane antisymmetry not ensured

When calculating the DA in the mid-plane, important differences were observed when using 2D or 3D fieldmaps. Only possible explanation: antisymmetry not ensured with 3D fieldmap.



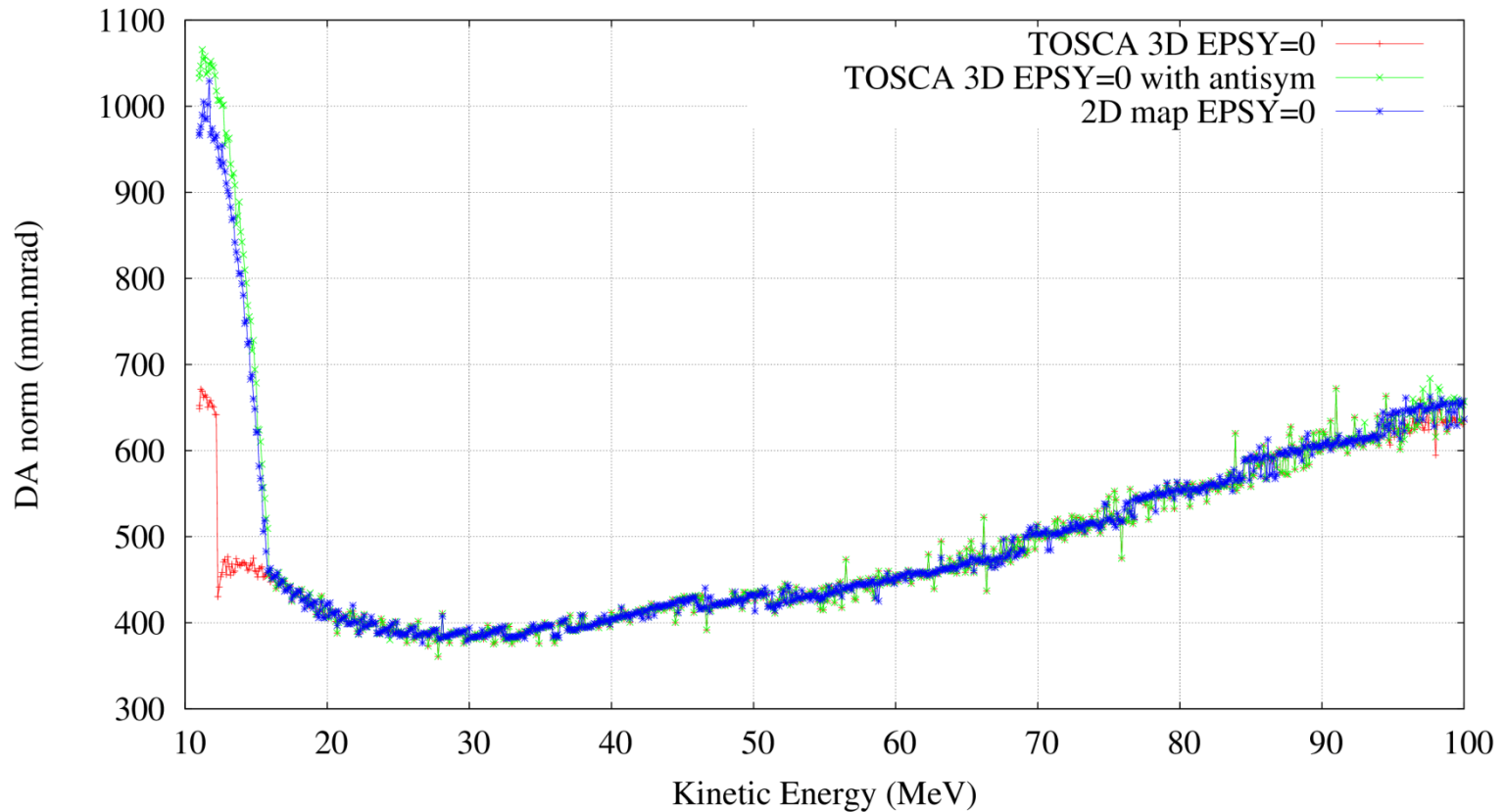
Field map plot of the B_x and B_y component in the median plane of the 150 MeV KURRI FFAG. If the median plane antisymmetry were ensured, one would obtain a blank map (zero everywhere). **Antisymmetry not ensured.**

3D map after ensuring the antisymmetry



The previous problem seem to arise from the B_x , B_y components that introduce some discontinuities in the calculation of the field and its derivatives in the median plane of the FFAG. Is the median plane antisymmetry guaranteed in real life?

Comparison of the different models



Mid-plane tracking with the 2D fieldmap and 3D fieldmap with antisymmetry yield similar results as expected.

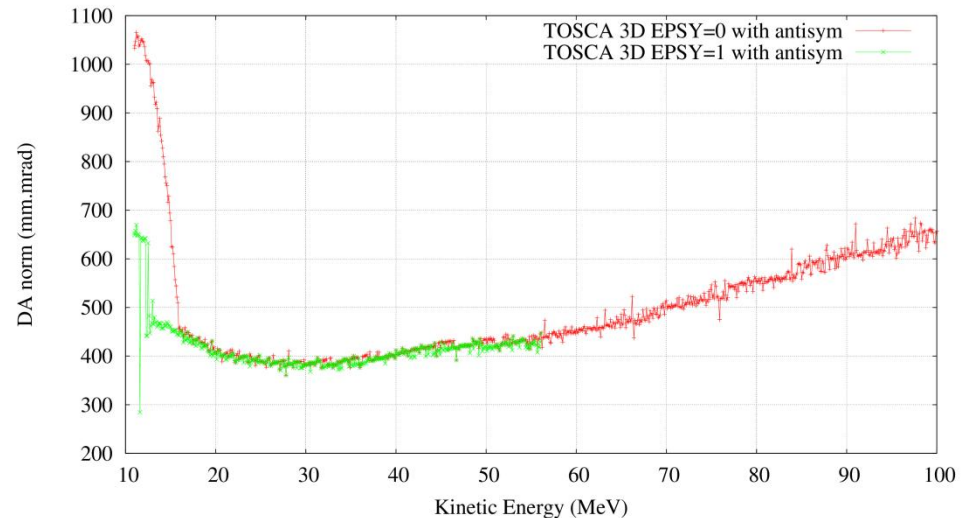
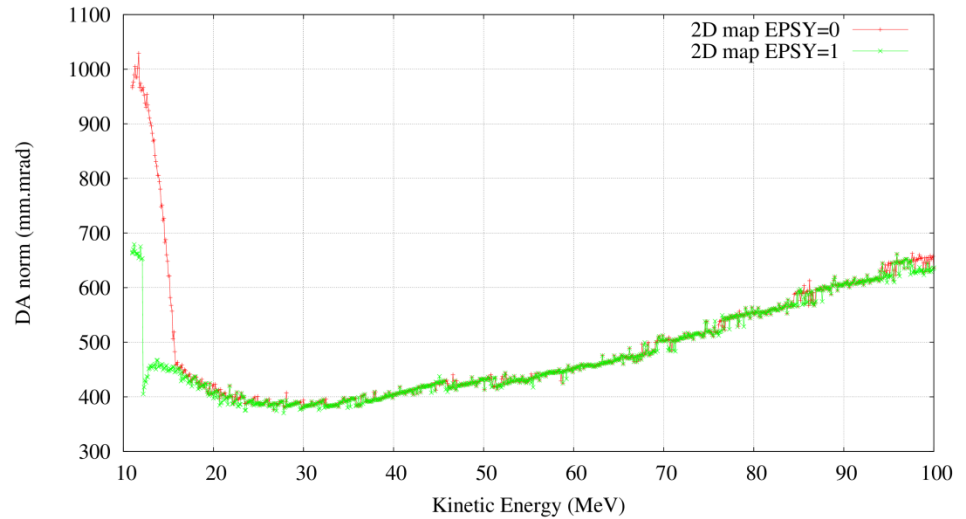
Difference with the 3D case is simply explained by the fact it is not antisymmetric.

Summary

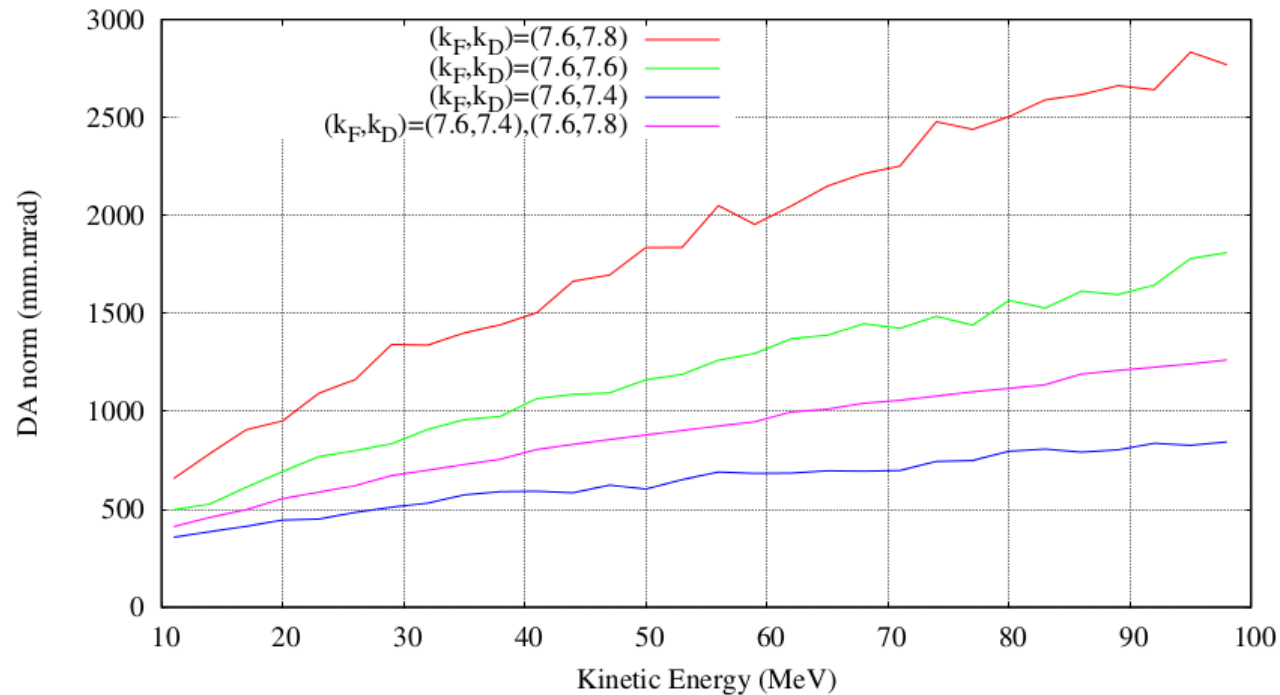
The DA calculation out of the mid-plane yield similar results between the 2D and 3D fieldmaps with and without antisymmetry.

In all cases, the DA is thus 375 mm.mrad

However, the tunes may be different which explains some dips that can be observed in one case or the other.



DA vs k_F k_D



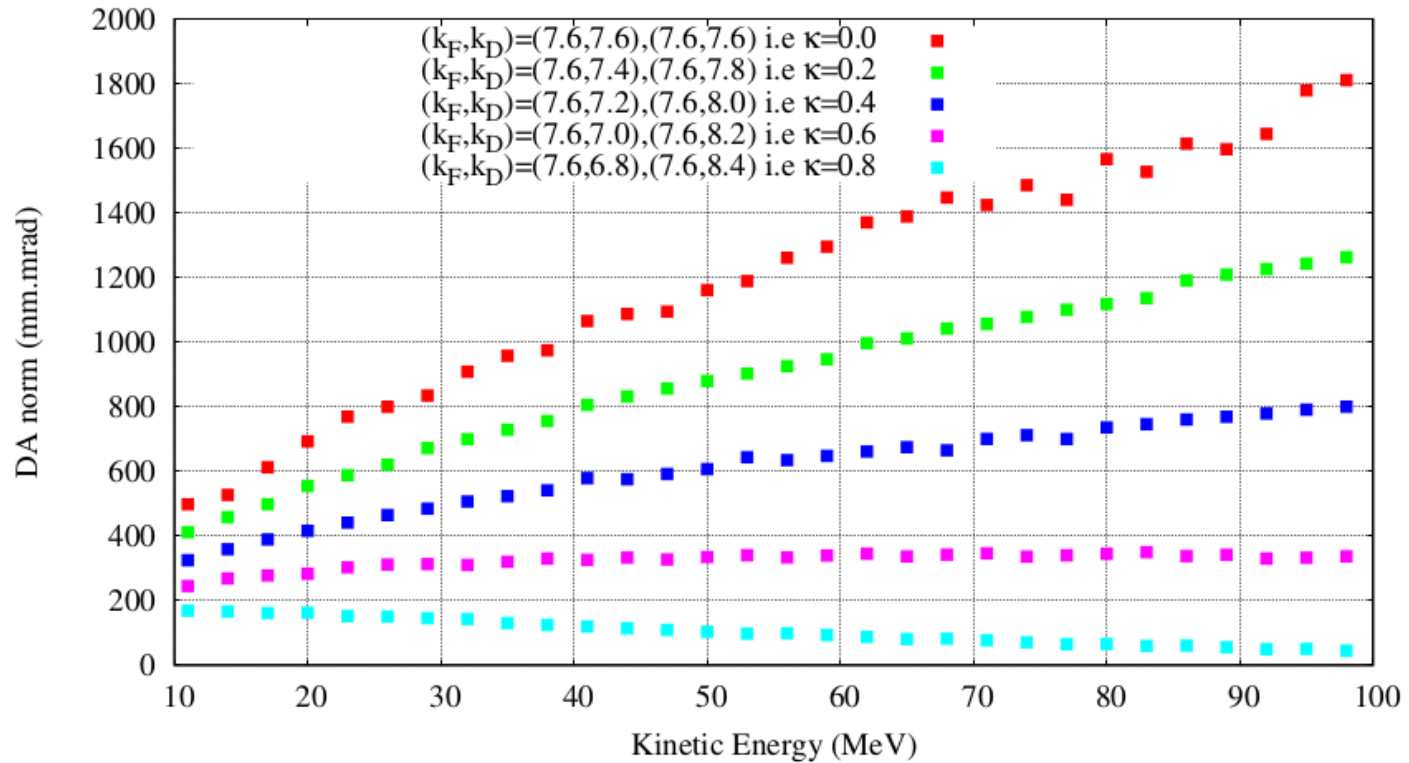
Increasing k_D generally increases the Dynamic Acceptance.

Therefore alternating the differences of k_F, k_D in order to fix the tune has a smaller DA than the equivalent scaling FFAG case.

This also shows that the DA is limited by any magnet which has $k_F > k_D$.

Generally speaking, $k_D > k_F$ ($\sim 9 > 7.6$) for the KURRI FFAG which explains the large DA simulated.

DA vs k_F - k_D



Increasing the differences of the scaling factors differences i.e. $\kappa = k_D - k_F$ decreases the DA of the machine.

As shown earlier, this is due to the magnets which have $k_F > k_D$.